O.P.Code: 20EE0225

R20

H.T.No.

L3

12M

SIDDHARTH INSTITUTE OF ENGINEERING & TECHNOLOGY:: PUTTUR (AUTONOMOUS)

B.Tech. III Year II Semester Regular & Supplementary Examinations June-2025 POWER SEMICONDUCTOR DRIVES

(Electrical & Electronics Engineering)

Time:	3 Hours					Ü	0,		Max.	Mark	s: 60
			(Answ	er all	Five U	Inits 5 x 12	= 60 Mark	(zs)			
					t	J NIT-I					
1 1	With neat	diagram	evnlain	1-0	fully	controlled	converter	fed by	COL	T A	12M

With neat diagram, explain 1-Ø fully controlled converter fed by CO1 L4 12M separately excited DC motor in continuous conduction mode.

OR

The speed of a 20HP, 210V. 1000rpm series dc motor is controlled by a 1-Ø fully controlled converter. The combined field and armature circuit resistance is 0.25Ω, Kaf=0.03N-m/ A2 and Kres=0.075 V-S/rad. The supply voltage is 230V. Assuming continuous and ripple free motor current, determine the following for a firing angle α=300 and speed N=1000 rpm. Find (i). The motor torque (ii). The motor current (iii). The supply power-factor

UNIT-II

3	Explain in detial about:	CO2	L2	12M
	a) Diversions			

a) Plugging

b) Dynamic braking

c) Regenerative braking

OR

4	a	Draw and explain operation of current limit control.	CO ₂	L2	6M
	b	Explain the operation of closed loop speed control of dc drive.	CO ₂	L2	6M
		UNIT-III			
5		Describe how the operation of second quadrant can be obtained from	CO ₃	1.2	12M

Describe how the operation of second quadrant can be obtained from CO3 L2 12M chopper fed by separately excited DC motor.

OR

6	A 230V,	10A,	1500rpm	separately	excited of	de moto	r with	armature	CO ₃	L3	12M
	resistance	of 1.5	Ω motor	operates un	der dynan	nic braki	ng wit	h chopper			
	control. B	raking	resistance	has a value	e of 15Ω .						
	(1) (2) 1 1										

(i) Calculate the duty ratio of chopper for motor speed of 1200rpm and braking torque equal to 2 times the rated motor torque.

(ii) What will be the motor speed for duty ratio of 0.6 and motor torque equal to twice the rated torque?

UNIT-IV

7	a Explain voltage control	method of Induction motor drive.	CO4	L2	6M
	b Explain stator- frequenc	y control method.	CO4	L2	6 M

OR

8 Explain the speed control method for 3-Ø induction motor bu using CO4 L2 12M Cycloconverter.

UNIT-V

9	a	Explain the operation of self - control of synchronous motor.	CO ₅	L2	6M
	b	Discuss the operation of separate -control of synchronous motor.	CO ₅	L2	6M

OR

Explain variable frequency control of synchronous motor by PWM CO5 L2 12M technique.

*** END ***